

MATRIKALSK - MATRICE BEREIT SATIGKE

Elementare Eigenschaften $A \sim B$ [Eigenschaften, die unter einer Zeilen- oder Spalten-Operation invariant sind]

- Matrizenmultiplikation

DETERMINANTE - KALKULIEREN - TRANSFORMATIONS

- Methoden $\left\{ \begin{array}{l} n=3 \rightarrow \text{Sarrus} \\ n>3 \rightarrow \text{Laplace} \end{array} \right.$ $\sum_{j=1}^n a_{ij} A_{ij}^*$

- Matrizenmultiplikation

Elemente multiplizieren, dann addieren, dann subtrahieren, dann dividieren, dann multiplizieren, dann addieren, dann subtrahieren, dann dividieren.

- Adjunkte $\rightarrow A_{ij} = (-1)^{i+j} M_{ji}$ $M_{ij} = \pm M_{ji}$

Ordnungsgesetz der Matrizenmultiplikation

* Determinante ist ein Skalar, der die Orientierung des Raumes angibt. Er ist invariant unter Zeilen- und Spaltenvertauschungen.

Kombinatorik

$a, b, c, \dots \in \mathbb{R}$

$aE_1 + bE_2 + \dots$

$E_i \pm E_j$

$2E_i + E_j$

Eigenschaften

1) $E_i \leftrightarrow E_j$ $\rightarrow \det A \rightarrow -\det A$

2) $\forall \lambda \in \mathbb{R}; \lambda E_i$ $\rightarrow \det A \rightarrow \lambda \cdot \det A$ [determinanten additiv]

3) $E_i \rightarrow E_i + [\lambda_1 E_j + \lambda_2 E_k + \dots]$ $\rightarrow \det A \rightarrow \det A$

Zeilen- und Spalten

Minoren

$h(A) \rightarrow$ Matrix

$h(A) \rightarrow$ Matrix

$h(A) = h(A^T)$ \rightarrow Determinante
 $h(A) \neq h(A^T)$ \rightarrow Determinante

Matrix

$A \in M_{m,n}(\mathbb{R}) / B \in M_{n,m}(\mathbb{R})$

$A \cdot B = B \cdot A = I_n$ $B = A^{-1}$

$A \rightarrow$ Matrix

Kalkulation

1) $A^{-1} = \frac{1}{\det(A)} \tilde{A}$ $\tilde{A} = (A_{ji}^*)$

2) Elementare Eigenschaften $\rightarrow A/S \rightarrow I_n/A$ 3) ELS

Matrix $\rightarrow \det = 0$
 \rightarrow Cholesky

$$A = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{pmatrix} \left| \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \right. \sim \begin{matrix} \frac{1}{2} E_1 \\ \frac{1}{3} E_2 \\ \frac{1}{4} E_3 \end{matrix} \left| \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \right. \left| \begin{pmatrix} 1/2 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/4 \end{pmatrix} \right. \quad \boxed{2) \text{ procedure}}$$

\downarrow
 A^{-1}

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \xrightarrow{R_3 - R_1} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \xrightarrow{\frac{1}{2} E_3} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 + R_3} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{\frac{1}{2} E_1} \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \boxed{1) \text{ procedure}}$$

\downarrow
 A^{-1}

$$A^3 - 3A^2 + 4A - 2I_3 = [0]_{3 \times 3}$$

- I_3 extract

- A is diagonalizable because extract

- $A [\quad] \cdot I_3$

- A^{-1} kalkulations formula given by

$$\frac{A^3 - 3A^2 + 4A}{2} = I_3$$

$$A \left[\frac{1}{2} (A^2 - 3A + 4I) \right] = I_3$$

$$2A^{-1} = A^2 - 3A + 4I \quad A^{-1} = \frac{1}{2} [A^2 - 3A + 4I]$$

$\boxed{4) \text{ procedure}}$

sol. b

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \quad A^2 = \begin{pmatrix} 0 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & 0 \end{pmatrix} - \begin{pmatrix} 3 & 0 & 3 \\ 0 & 3 & 0 \\ 3 & 0 & 3 \end{pmatrix} + \begin{pmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$\frac{1}{2} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1 & 0 \\ -1/2 & 0 & 1/2 \end{pmatrix} = A^{-1}$$

Eigenschaften inverser Matrizen

$$A \cdot B = C \Rightarrow A \cdot B \cdot B^{-1} = C \cdot B^{-1} \Rightarrow A = C \cdot B^{-1}$$

$$\Rightarrow A^{-1} \cdot A \cdot B = A^{-1} \cdot C \Rightarrow B = A^{-1} \cdot C$$

$$A \cdot B \cdot C = D \Rightarrow A \cdot (B \cdot C) = D \Rightarrow A \cdot (B \cdot C) \cdot (B \cdot C)^{-1} = D \cdot (B \cdot C)^{-1} \Rightarrow A = D \cdot (B \cdot C)^{-1}$$

$$\Rightarrow A^{-1} \cdot A \cdot B \cdot C \cdot C^{-1} = A^{-1} \cdot D \cdot C^{-1} \Rightarrow B = A^{-1} \cdot D \cdot C^{-1}$$

$$\Rightarrow (A \cdot B) \cdot C = D \Rightarrow (A \cdot B) \cdot (A \cdot B)^{-1} \cdot C = (A \cdot B)^{-1} \cdot D \Rightarrow C = (A \cdot B)^{-1} \cdot D$$

$$(A \cdot B)^T = B^T \cdot A^T$$

$$(A^T)^T = A$$

$$(A \cdot B)^{-1} = B^{-1} \cdot A^{-1}$$

$$(A^{-1})^{-1} = A$$

$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$x = A^{-1}y$$

$$\Rightarrow \begin{cases} x_1 - x_3 = y_1 \\ x_2 = y_2 \\ x_1 + x_3 = y_3 \end{cases} \quad A/A = \left(\begin{array}{ccc|c} 1 & 0 & -1 & y_1 \\ 0 & 1 & 0 & y_2 \\ 1 & 0 & 1 & y_3 \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & 0 & 0 & \frac{y_1 + y_3}{2} \\ 0 & 1 & 0 & y_2 \\ 0 & 0 & 1 & y_3 - \frac{y_1 + y_3}{2} \end{array} \right)$$

$$K_2 = y_2$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1 & 0 \\ -1/2 & 0 & 1/2 \end{pmatrix} \cdot \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$\det(A) = \kappa \quad \det(A^{-1}) = \frac{1}{\kappa}$$
$$W^{\mu} \cdot (\Delta)^{\mu}$$

$$\Delta^0 = [0]_{n,n} \quad \Delta \text{ singular}$$

$$[\det \Delta]^0 = 0$$

$$\Downarrow$$

$$\det \Delta = 0$$

$$|\Delta| = 0$$

Δ orthogonal

$$\Delta^T = \Delta^{-1} \Rightarrow \Delta \cdot \Delta^T = \Delta^T \cdot \Delta = I$$

$$\Delta \Delta^{-1} = \Delta^{-1} \Delta = I$$

$$\Delta \cdot \Delta^T = \Delta^T \cdot \Delta$$

$P = \Delta^{-1} \Delta^T$ orthogonale det. positiv.

$$P P^T = I, \quad \Delta^{-1} \Delta^T P^T = \boxed{\Delta^{-1} \Delta^T (\Delta^T)^T} = \Delta^{-1} \Delta^T (\Delta^T)^T \cdot (\Delta^{-1})^T = \Delta^{-1} \Delta^T \Delta \cdot (\Delta^{-1})^T = \Delta^{-1} \Delta \cdot \Delta^T \cdot (\Delta^{-1})^T$$

$$\downarrow \quad \quad \quad \downarrow$$

$$(\Delta^{-1} \Delta^T)^T \quad (A \cdot B)^T = B^T \cdot A^T \quad \quad \quad I \cdot I = I$$

ERLAGSKERNE ALGEBRAEKTIONEN

$$A \cdot B = C \rightarrow A B B^{-1} = C \cdot B^{-1} \rightarrow A = C B^{-1}$$

$$\rightarrow A^{-1} A B = A^{-1} C \rightarrow B = A^{-1} C$$

$$A B C = D \rightarrow A (B C) = D \rightarrow A (B C) (B C)^{-1} = D (B C)^{-1} \rightarrow A = D (B C)^{-1}$$

$$\rightarrow A^{-1} A B C C^{-1} = A^{-1} D C^{-1} \rightarrow B = A^{-1} D C^{-1}$$

$$\rightarrow (A B) C = D \rightarrow (A B) (A B)^{-1} C = (A B)^{-1} D \rightarrow C = (A B)^{-1} D$$

$$(A B)^T = B^T A^T \quad (A^{-1})^T = A$$

$$(A B)^{-1} = B^{-1} A^{-1} \quad (A^{-1})^{-1} = A$$

$$\det(A B) = \det A \cdot \det B \quad A A^{-1} = A^{-1} A = I$$

$$\det A = 3 \quad (\det A^{-1})(\det A) = \det I$$

$$\det A^{-1} = ? \quad \det A^{-1} \cdot 3 = 1 \quad \det A^{-1} = 1/3$$

$$\Delta^T = \Delta^{-1} \rightarrow \text{Matrixe orthogonal}$$

$$\det A? \quad A \cdot \Delta^T = I \quad \det A^T \det A = 1 \quad | \quad (\det A)^2 = 1 \quad \det A = \pm 1$$

$$\det A = \det A^T$$

A. Kette

$$A, B \in M_{n \times n}(\mathbb{R}) \quad / \quad A \cdot B = B \cdot A$$

$$\text{Idempotenten} \quad \left. \begin{array}{l} A^2 = A \\ B^2 = B \end{array} \right\}$$

$$\text{Frage: } (A+B)^3 (A-B) = A-B$$

$$(A+B)^2 (A+B) (A-B) = A-B$$

$$(A^2 + 2AB + B^2) (A-B) = A-B$$

$$(A + 2AB + B) (A-B) = A-B$$

$$\cancel{A^2} - \cancel{AB} + \cancel{2A^2B} - \cancel{2AB^2} + \cancel{AB} - B^2 = A-B$$

$$\boxed{A-B = A-B}$$

$$A, B \in M_{n \times n}(\mathbb{R}) \quad \text{Frage:}$$

$$A \text{ ist symmetrisch d.h.}$$

$$A = A^T \quad (A = A^T)^T = A^T = A$$

$$A \text{ und } B \text{ symmetrisch} \Rightarrow (A+B)^2 \text{ symmetrisch} \quad \forall n \in \mathbb{N}$$

$$A = B^T \quad B = A^T$$

$$(A+B)^n = (B^T + A^T)^n = [(B+A)^T]^n = [(A+B)^T]^n$$

$$A \text{ und } B \text{ antisymmetrisch} \rightarrow \forall n \text{ beliebig } \in \mathbb{N} \rightarrow (A+B)^n \text{ symmetrisch}$$

$$\forall n \text{ beliebig } \in \mathbb{N} \rightarrow (A+B)^n \text{ antisymmetrisch}$$

$$A = -A^T \rightarrow -A = A^T$$

$$B = -B^T \rightarrow -B = B^T$$

$$\begin{aligned} [(A+B)^n]^T &= [(-A)(A^T+B^T)]^n = (-1)^n [(A+B)^{T,n}]^T \\ &= (-1)^n (A+B)^n \end{aligned}$$

$$[(A+B)^n]^T = \begin{cases} n=2k \rightarrow (A+B)^n \\ n=2k-1 \rightarrow -(A+B)^n \end{cases}$$

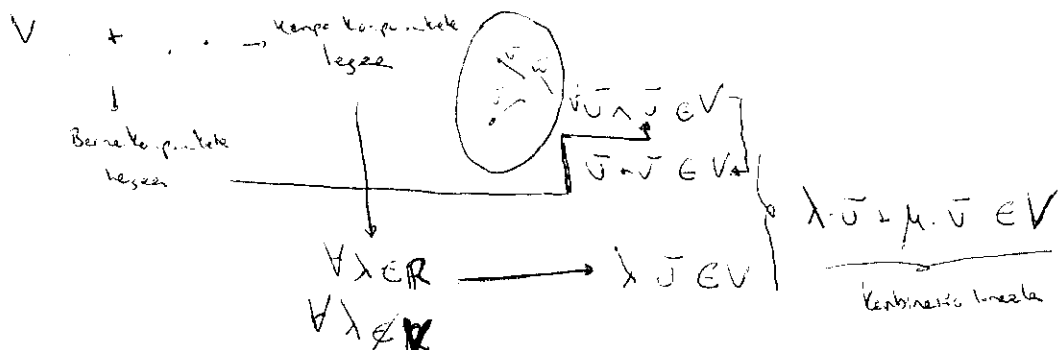
$$A \text{ und } B \text{ antisym.} : A \cdot B \text{ sym} \Leftrightarrow A \cdot B = B \cdot A$$

$$\left. \begin{array}{l} A^T = -B \quad B^T = -A \quad (AB)^T = [(-B^T) \cdot (-A^T)]^T = (B^T A^T)^T = [(BA)^T]^T = BA \\ A \cdot B \text{ sym} \Rightarrow (AB)^T = AB \end{array} \right\} A \cdot B = B \cdot A$$

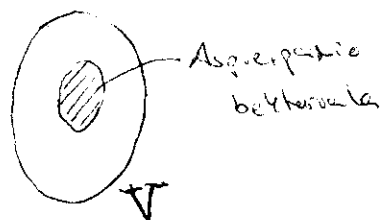
$A \in M_{n \times n}(\mathbb{R})$ ist eine nilpotente singuläre Matrix.

$$A^p = [0]_{n \times n} \quad \det(A^p) = \det[0]_{n \times n} = 0$$

$$(\det A)^p = \det[0]_{n \times n} \quad (\det A)^p = 0 \rightarrow \det A = 0$$



$$V \left\{ \begin{array}{l} \mathbb{R}^n, n \in \mathbb{N} \left\{ \begin{array}{l} \mathbb{R}^2 \Rightarrow (a, b) \quad a, b \in \mathbb{R} \\ \mathbb{R}^3 \Rightarrow (a, b, c) \quad a, b, c \in \mathbb{R} \\ \mathbb{R}^4 \Rightarrow (a, b, c, d) \quad a, b, c, d \in \mathbb{R} \end{array} \right. \\ \mathcal{P}_n; \forall \vec{v} \in \mathcal{P}_n / \vec{v} = \sum_{i=0}^n a_i x^i = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n \\ M_{n \times n}(\mathbb{R}) \\ C, [a, b] \text{ gerade} \end{array} \right.$$



F: Bektore-systeme $\left\{ \begin{array}{l} \text{Systeme linear} \\ \text{Systeme nicht linear} \end{array} \right.$

Bektore-systeme haben keine: $h(F)$

Aufg

$$F = \{(1, 2), (2, 3)\} \subset \mathbb{R}^2 \rightarrow \text{Bektore systeme}$$

$$h(F) = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} = 2 \rightarrow \text{Zwei bektore linear unabhängige vektoren} \rightarrow h(F) = 2 = m_K \rightarrow \text{Systeme linear}$$

$$G = \{(1, 2), (2, 1)\} \subset \mathbb{R}^2$$

$$h(G) = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = 1 \Rightarrow h(G) = 1 < m_K \rightarrow \text{Systeme linear}$$

m_K = bektore kopieren

$$M = \{x^2, 3-2x, x^2+2x-3\} \subset \mathcal{P}_2 \Rightarrow M = \{(0, 0, 1), (3, -2, 0), (-3, 2, 1)\}$$

$$h(M) = \begin{pmatrix} 0 & 0 & 1 \\ 3 & -2 & 0 \\ -3 & 2 & 1 \end{pmatrix} = 2 \rightarrow h(M) = 2 < m_K \rightarrow \text{Systeme linear}$$

$$H = \left\{ \begin{pmatrix} 2 & 3 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} -3 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 6 \\ 1 & 0 \end{pmatrix} \right\}$$

$$H^1 = \left\{ (2, 3, 0, 0), (-3, 0, 1, 0), (1, 6, -1, 0) \right\}$$

$$h(H) = \begin{pmatrix} 2 & 3 & 0 & 0 \\ -3 & 0 & 1 & 0 \\ 1 & 6 & -1 & 0 \end{pmatrix} = 2 \text{ ∞ er systeme lösbar}$$

1.2 Aufgabe

a) Are spanne die Vektoren ab? $\vec{u}, \vec{v} \in \mathbb{R}^3$

$$S = \{ (0, a, b) \mid a, b \in \mathbb{R} \} \subset \mathbb{R}^3$$

$$(0, a, b) = (0, a, 0) + (0, 0, b) = a(0, 1, 0) + b(0, 0, 1)$$

$$\vec{v} \in S: \vec{v} = (0, a_1, b_1)$$

$$\vec{w} = (0, a_2, b_2)$$

$$\vec{v} + \vec{w} = (0, a_1 + a_2, b_1 + b_2) \in S? \text{ Bei beiden exp. spanne die Vektoren.}$$

$$T = \{ (0, a, 1) \mid a \in \mathbb{R} \}$$

$$\vec{u} = (0, 0, 1) \in T$$

$$\vec{v} = (0, 1, 2) \notin T$$

$$\vec{w} = (0, 2, 1) \in T$$

$$\vec{v} + \vec{w} = (0, 2, 2) \notin T$$

$$\vec{u} = (0, a_1, 1); \lambda \vec{u} = \lambda(0, a_1, 1)$$

$$\vec{v} = (0, a_2, 1)$$

$$\vec{v} + \vec{w} = (0, a_1 + a_2, 2) \notin T$$

Es ist nicht spanne die Vektoren

$$E = \{ (x, y, z) \mid x + y = 0 \wedge x - y = z \}$$

$$\vec{u} = (x_1, y_1, z_1)$$

$$\vec{v} = (x_2, y_2, z_2)$$

$$\vec{u} + \vec{v} = \begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{pmatrix} \in E \quad \begin{cases} x_1 + y_1 = 0 \\ x_2 + y_2 = 0 \end{cases}$$

$$\vec{u} \in E: x_1 + y_1 = 0 \wedge x_1 - y_1 = z_1$$

$$\vec{v} \in E: x_2 + y_2 = 0 \wedge x_2 - y_2 = z_2$$

$$(x_1 + x_2)(y_1 + y_2) = 0 \quad (x_1 + x_2)(y_1 + y_2) = z_1 + z_2$$

$$x_1 + y_1 = 0 \quad x_2 + y_2 = 0$$

$$\lambda(x, y, z) \in E?$$

$$\lambda(x, y, z) \in E$$

$$\lambda(x + y) = 0$$

$$\lambda(x - y) = \lambda z$$

$$\lambda(x + y) = 0 \quad x + y = 0$$

$$\lambda(x - y) = \lambda z \quad x - y = z$$

Are spanne die Vektoren ab?

Bektore-sisteme baten itxidura lineala

$$F = \{(1,0,0), (0,1,0)\}$$

$$h(F) = h \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} = 2 \rightarrow \text{Sistema bastea}$$

Bektoreekin, kombinazio linealen bidez, itxidura lineala sortu dezakegu. Itxidura lineala multzo bat da.

Arre espazio bektoriala $\rightarrow S = \mathcal{L}(F) = \mathcal{L}(B_S)$

$\left\{ \begin{array}{l} S, \text{ asken} \rightarrow S\text{-ren oinarria} \\ S, \text{ lotua} \end{array} \right\}$

$\left\{ \begin{array}{l} S\text{-ren sortutakoak} \\ Sistema\text{-sortutakoak} \end{array} \right\}$

► Bektore kopurua: kardinalitate

$$h(B_S) = h = \dim S$$

Hierre: $h(F) \begin{cases} h(F) = m & \text{asken} \\ h(F) < m & \text{lotua} \end{cases}$

$\left\{ \begin{array}{l} \text{Bektore linealki} \\ \text{independenteak} \end{array} \right\} \rightarrow \text{Bektore kopurua}$

$$\dim S \leq \dim V$$

↳ V-ren arre espazio kopurua da S

$$\dim S = \dim V$$

$$\hookrightarrow S = V$$

$$\dim S \geq 1$$

↳ Dimentsioa beti itxerga da hantzean edo budi bati

$$S = \{(x_1, x_2, x_3) / x_1 = 2x_2 + x_3\}$$

$$h(F) = h \begin{pmatrix} 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} = 2 = \text{bekt. kop.}$$

$$\vec{u} = (2x_2 + x_3, x_2, x_3) \quad \vec{u} = (2, 1, 0) \in S \quad \left\{ \begin{array}{l} u, v \in S? \\ \lambda u \in S? \end{array} \right. \quad \begin{array}{l} (3, 1, 1) \text{ Bai} \\ (4, 2, 1) \text{ Bai} \end{array}$$

$$S = \mathcal{L}(F)$$

$$(2x_2, x_2, 0) + (x_3, 0, x_3) \Rightarrow x_2(2, 1, 0) + x_3(1, 0, 1) \Rightarrow F = \{(2, 1, 0), (1, 0, 1)\} \rightarrow \text{Sistema bastea}$$

$$T = \{(x_1, x_2, x_3) / 2x_1 + x_2 = 8x_3, x_3 = 0\} \quad x_1 = -\frac{x_2}{2} \quad x_1 = -\frac{x_3}{3} \quad x_2 = -2x_1 \quad x_2 = \frac{2x_3}{3}$$

$$\mathcal{L}(F) = T \quad \dim T =$$

$$\vec{u} = x_3(-1/3, 2/3, 1) \quad \begin{array}{l} n = 2 \text{ zeretarako} \rightarrow 2 \text{ zeretarako} \\ 3 \text{ zeretarako} \rightarrow 1 \text{ zeretarako} \end{array}$$

$$F = \{(-1/3, 2/3, 1)\}$$

$$W = \{(1, m, n) / m, n \in \mathbb{R}\} \quad (1, 0, 0) + m(0, 1, 0) + n(0, 0, 1) \quad F = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$$

$$S = \{(x_1, x_2, x_3, x_4) / x_3 = 0 \wedge x_1 + x_2 + x_4 = 0\}$$

$$\vec{u}_1 = (-x_2 - x_4, x_2, 0, x_4)$$

$$x_2(-1, 1, 0, 0) + x_4(-1, 0, 0, 1)$$

$$h(F) = h \begin{pmatrix} -1 & 1 & 0 & 0 \\ -1 & 0 & 0 & 1 \end{pmatrix} = 2 = \text{bekt. kop.}$$

$$F_S = \{(-1, 1, 0, 0), (-1, 0, 0, 1)\}$$

$$\dim S = 2$$

$$S = \mathcal{L}(F)$$

$$F = \left\{ \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 3 & 0 \\ 1 & 0 \end{pmatrix} \right\} \quad \begin{array}{l} \text{Sistema teste} \\ \text{etc} \\ \text{lotaria de?} \end{array}$$

$S = \mathcal{L}(F)$ - espaço linear com dimensão

$$\{ (1, 1), (0, 1), (1, 0) \}$$

$$\{ (0, 1), (1, 0) \}$$

$$\{ (3, 0), (1, 0) \}$$

$$h(F) = h \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 3 & 0 & 1 & 0 \end{pmatrix} = 3 = \text{básis} \quad \begin{array}{l} \text{Sistema teste} \end{array}$$

Sistema teste = linearmente independente $\dim = 3$

$$G = \left\{ \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 3 & 5 \\ 1 & 0 \end{pmatrix} \right\}$$

$$h(G) = h \begin{pmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 3 & 5 & 1 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{pmatrix} = 2 \neq \text{básis} \quad \begin{array}{l} \text{Sistema teste} \end{array}$$

$\det = 0$

$$T = \mathcal{L}(G)$$

$$\dim T = 2 \quad B_T = \left\{ \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right\} = \left[\text{matrizes} \right]$$

$$S \subset \mathbb{R}^2$$

$$L \subset \mathbb{R}^3$$

$$B_S \rightarrow B_{\mathbb{R}^3}?$$

$$B_L \rightarrow B_{\mathbb{R}^3}?$$

B_S linearmente independente $\rightarrow B_{\mathbb{R}^3}$

$\hookrightarrow S$ esp. linearmente independente

$S \subset V \rightarrow$ Base de V

V-esp. linearmente independente \hookrightarrow Sistema teste

$$B_S = \{ (0, 1, 0), (0, 0, 1) \} \rightarrow B_{\mathbb{R}^3} = \{ (0, 1, 0), (0, 0, 1), (1, 0, 0) \}$$

$$h(B_{\mathbb{R}^3}^1) = h \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = 3$$

$$B_L = \{ (1, -1, 2) \} \rightarrow B_{\mathbb{R}^3}^2 = \{ (1, -1, 2), (0, 1, 0), (0, 0, 1) \}$$

$$h(B_{\mathbb{R}^3}^2) = h \begin{pmatrix} 1 & -1 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = 3$$

Base \rightarrow base de V \rightarrow sistema teste
linearmente independente

1.3 Aufgabe

$$S = \{ (x_1, x_2, x_3, x_4) \mid x_3 = 0 \wedge x_1 + x_2 + x_3 + x_4 = 0 \}$$

$$B_S = \{ (1, -1, 0, 0), (0, -1, 0, 1) \} \Rightarrow B_{\mathbb{R}^4} = \{ (1, -1, 0, 0), (0, -1, 0, 1), (0, 0, 1, 0), (0, 0, 0, 1) \}$$

$$h(B_{\mathbb{R}^4}) = h \begin{pmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = 4$$

$S \subset \mathbb{R}^4 \rightarrow \dim \mathbb{R}^4 = 4$ linearisierbare betr. K_2 .

$$B_S = \{ (1, -1, 2, 2), (1, 2, 3, 4) \} \rightarrow B_{\mathbb{R}^4} = \{ (1, -1, 2, 2), (1, 2, 3, 4), (0, 0, 1, 0), (0, 0, 0, 1) \}$$

$$h(B_{\mathbb{R}^4}) = 4 = h \begin{pmatrix} 1 & -1 & 2 & 2 \\ 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \stackrel{\bar{E}_1 - E_2}{=} h \begin{pmatrix} 1 & -1 & 2 & 2 \\ 0 & 3 & 1 & 2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$S_T = \{ (1, -1, 0, 2), (1, 2, 0, 4), (3, 2, 0, -3) \} \rightarrow S_{\mathbb{R}^4} = \{ (1, -1, 0, 2), (1, 2, 0, 4), (3, 2, 0, -3), (0, 0, 1, 0) \}$$

$$\left[h(S_{\mathbb{R}^4}) = h \begin{pmatrix} 1 & -1 & 0 & 2 \\ 1 & 2 & 0 & 4 \\ 3 & 2 & 0 & -3 \\ 0 & 0 & 1 & 0 \end{pmatrix} = h \begin{pmatrix} 1 & -1 & 0 & 2 \\ 0 & 3 & 0 & 2 \\ 0 & 5 & 0 & -9 \\ 0 & 0 & 1 & 0 \end{pmatrix} \right]$$

Dimension $d = ?$
 Bei $h(S_{\mathbb{R}^4}) =$ betr. K_2 linear

$$h(S_{\mathbb{R}^4}) = h \begin{pmatrix} 1 & -1 & 0 & 2 \\ 1 & 2 & 0 & 4 \\ 3 & 2 & 0 & -3 \end{pmatrix} = h \begin{pmatrix} 1 & -1 & 2 \\ 1 & 2 & 4 \\ 3 & 2 & -3 \end{pmatrix} = h \begin{pmatrix} 1 & -1 & 2 \\ 0 & 3 & 2 \\ 0 & 5 & -9 \end{pmatrix} = 3$$

$$B_{\mathbb{R}^4}^T = \{ (1, -1, 0, 2), (1, 2, 0, 4), (3, 2, 0, -3), (0, 0, 1, 0) \}$$

$$\begin{pmatrix} 1 & -1 & 0 & 2 \\ 1 & 2 & 0 & 4 \\ 3 & 2 & 0 & -3 \\ 1 & 0 & 1 & 0 \end{pmatrix}$$

1.1.1.1.1.1

$$B = \{x^2 + x + 1, x^2 + x, x^2\}$$

$$\downarrow \quad \downarrow \quad \downarrow$$

$$\bar{e}_1 \quad \bar{e}_2 \quad \bar{e}_3$$

$$B = B_{P_2}?$$

$$h(B_{P_2}) = h \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} = 3$$

$$\left[\begin{array}{ccc|ccc|ccc|ccc|ccc} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right] \rightarrow 3$$

$$B = \{(x, 1, 0), (0, 0, x+2), (1, 1, 1)\} \quad x \in \mathbb{R} \Leftrightarrow B' = B_{\mathbb{R}^3}$$

$$h(B') = h \begin{pmatrix} x & 1 & 0 \\ 0 & 0 & x+2 \\ 1 & 1 & 1 \end{pmatrix} \xrightarrow{A_{B'}}$$

$$\det(A_{B'}) = \begin{vmatrix} x & 1 & 0 \\ 0 & 0 & x+2 \\ 1 & 1 & 1 \end{vmatrix} = -(x+2) \begin{vmatrix} x & 1 \\ 1 & 1 \end{vmatrix} = -(x+2)(x-1) = 0$$

$$x+2=0 \quad x=-2 \quad \checkmark$$

$$x-1=0 \quad x=1 \quad \checkmark$$

$$1. \text{ Fall } x \in \{-2, 1\} \rightarrow h(A_{B'}) = 2 \quad \text{Bz}$$

$$2. \text{ Fall } x \in \mathbb{R} - \{-2, 1\} \rightarrow h(A_{B'}) = 3 \quad \text{Bei einerseits}$$

$$S = \{(x_1, x_2, x_3, x_4) \mid x_1 = x_2\}, \quad T = \{(1, 1, 2, 1), (2, 0, -1, 1)\} = L(S_T)$$

$$\mathbb{R}^3 \rightarrow L(B_C) = \mathbb{R}^3$$

$$L(B_C) = L(\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\})$$

$$\vec{v} = (x_1, x_2, x_3, x_4) = (x_1, x_1, x_3, x_4) = x_1(1, 1, 0, 0) + x_3(0, 0, 1, 0) + x_4(0, 0, 0, 1)$$

$$h(S_S) = h \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = 3 \quad \text{B} = \text{bett. kop} \rightarrow \text{Subräume einerseits}$$

$$h(S_T) = h \begin{pmatrix} 1 & 1 & 2 & 1 \\ 2 & 0 & 1 & 1 \end{pmatrix} = 2 \quad \text{bett. kop} \rightarrow \text{Subräume einerseits}$$

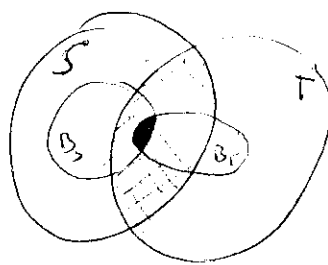
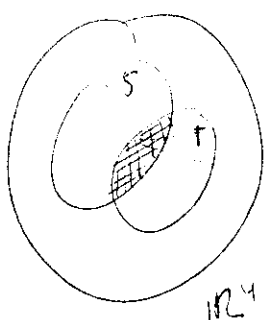
$$B_S = \{(1, 1, 0, 0), (0, 0, 1, 0), (0, 0, 0, 1)\}$$

$$B_T = \{(1, 1, 2, 1), (2, 0, -1, 1)\}$$

$$\vec{v}_T \quad \vec{v}_T$$

$$h \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 1 \end{pmatrix} = h \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 0 \end{pmatrix} = 3 \quad \left[\begin{array}{l} \text{ex. d. d. d.} \\ \text{Kombinationen} \end{array} \right]$$

Kombinationen linearer Abh. von \vec{v}_T lang. von \vec{v}_T nicht linear. \vec{v}_T nicht 0 sein. \vec{v}_T nicht 0 sein. \vec{v}_T nicht 0 sein.



$$B_{S \cap T} = \{\vec{v}_T\}$$

$$h \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 2 & 0 & 1 & 1 \end{pmatrix} = h \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 2 & 0 & 1 & 0 \end{pmatrix} = 4$$

$$S \subset \mathcal{P}_3 \quad S = \{p(x) \in \mathcal{P}_3 \mid p(1) = p(-1) \wedge p'(1) = 0\}$$

$$p(x) = ax^3 + bx^2 + cx + d$$

$$\begin{aligned} p(1) &= a + b + c + d \\ p(-1) &= -a + b - c + d \end{aligned} \quad \left\{ \begin{aligned} a + b + c + d &= -a + b - c + d \Rightarrow a + c = -(a + c) \Rightarrow 2(a + c) = 0 \\ a + b + c + d &= -a + b - c + d \Rightarrow a + c = 0 \end{aligned} \right.$$

$$p'(x) = 3ax^2 + 2bx + c$$

$$p'(1) = 3a + 2b + c = 0$$

$$\begin{aligned} 3a + 2b + c &= 2a + 2c \\ a + 2b - c &= 0 \end{aligned}$$

$$\begin{aligned} 2a &= -2c \\ a &= -c \quad c = -a \end{aligned}$$

$$p(x) = -cx^3 - 2cx^2 + cx + d$$

$$p(x) = ax^3 - 2ax^2 - ax + d$$

$$a(x^3 - 2x^2 - x) + d$$

$$\updownarrow$$

$$(d, -a, -a, a)$$

$$d(1, 0, 0, 0) + a(0, -1, -1, 1) \Leftrightarrow (d, 0, 0, 0) + (a, -a, -a, a)$$

$$h(b) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 1 \end{pmatrix} = 2$$

$$\mathcal{B}_S = \{1, -x - x^2 + x^3\}$$

$$(V, \langle \cdot, \cdot \rangle) \rightarrow \mathbb{R}^n, \mathcal{P}_n, \mathcal{M}_{m,n}(\mathbb{R}), \mathbb{C}, [a, b]$$

bektoren

bilkele
eskilama

norma euklideana (bektore baktel)^{*1}
 distantsia (bektoreen arteko)^{*2}
 proiektioa (\vec{x}, \vec{y} gertuko)^{*3}

ortogonalaketa (norma baktel)
 bilkelele lineal baktel

$$\langle x, x^2 \rangle = \int_{-1}^1 x^3 dx = \left[\frac{x^4}{4} \right]_{-1}^1 = \frac{1}{4} [1^4 - (-1)^4] = 0$$

$$*1 \quad \|\vec{x}\| = \sqrt{\langle \vec{x}, \vec{x} \rangle}$$

$$*2 \quad \|\vec{x} - \vec{y}\| = d(\vec{x}, \vec{y}) = \sqrt{\langle \vec{x} - \vec{y}, \vec{x} - \vec{y} \rangle}$$

$$*3 \quad P_{\vec{y}} \vec{x} = \frac{\langle \vec{x}, \vec{y} \rangle}{\|\vec{y}\|^2} \vec{y}$$

$$\cos \theta = \frac{\langle \vec{x}, \vec{y} \rangle}{\|\vec{x}\| \|\vec{y}\|} \quad \cos \theta = \frac{16}{14 \cdot \sqrt{21}} = \frac{4}{\sqrt{21}}$$

Adib

$$\vec{x} = (1, 2, 3)$$

$$\vec{y} = (2, 1, 4)$$

$$\|\vec{x}\| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{14}$$

$$\|\vec{y}\| = \sqrt{2^2 + 1^2 + 4^2} = \sqrt{21}$$

$$d(\vec{x}, \vec{y}) = \sqrt{(-1)^2 + 3^2 + (-1)^2} = \sqrt{11}$$

$$\vec{x} - \vec{y} = (-1, 1, -1)$$

$$P_{\vec{y}} \vec{x} = \frac{16}{21} \cdot (2, 1, 4) = \left(\frac{32}{21}, \frac{16}{21}, \frac{64}{21} \right)$$

$$P_{\vec{x}} \vec{y} = \frac{16}{14} \cdot (1, 2, 3) = \frac{8}{7} (1, 2, 3) = \left(\frac{8}{7}, \frac{16}{7}, \frac{24}{7} \right)$$

OSNARET baten ORTOGONALKETA

$$B_S = (\bar{v}_1, \bar{v}_2, \dots, \bar{v}_r) / L(B_S) = S \quad \text{ortogonal bertsatua}$$

$$B_{OS} = (\bar{v}_1, \bar{v}_2, \dots, \bar{v}_r) \quad L(B_{OS}) = S$$

$$B_{OS} = \{\bar{v}_1, \bar{v}_2, \dots, \bar{v}_r\}$$

B_{OS} ortogonal otegiak

Bertsatuek bertsatuekin elkarren
arteko biderketa eskalarrek
zero eman behar du.

$$\mathbb{R}^3: B_{OS} = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$$

$$\begin{array}{ccc} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} & \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} & \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} \\ \downarrow & \downarrow & \downarrow \\ 0 & 0 & 0 \end{array}$$

GRAM-SCHMIDT
prozedura

$$\begin{aligned} \bar{v}_1 &= v_1 \\ \bar{v}_2 &= v_2 - \frac{\langle v_2, \bar{v}_1 \rangle}{\|\bar{v}_1\|^2} \bar{v}_1 = v_2 - P_{v_1} v_2 \\ \bar{v}_3 &= v_3 - \frac{\langle v_3, \bar{v}_1 \rangle}{\|\bar{v}_1\|^2} \bar{v}_1 - \frac{\langle v_3, \bar{v}_2 \rangle}{\|\bar{v}_2\|^2} \bar{v}_2 \\ &= v_3 - P_{v_1} v_3 - P_{v_2} v_3 \\ \bar{v}_4 &= v_4 - P_{v_1} v_4 - P_{v_2} v_4 - P_{v_3} v_4 \end{aligned}$$

$$B_S = \{(1, 2, 0), (3, 0, 4)\} / S = L(B_S)$$

Ortogonalak da? $1 \cdot 3 + 2 \cdot 0 + 0 \cdot 4 = 3 \neq 0$, ez da ortogonalak
Beraz ortogonalak

$$B_{OS} = (\bar{v}_1, \bar{v}_2) = (\bar{v}_1, \bar{v}_2) \quad \bar{v}_1 = v_1 \quad B_{OS} = \{(1, 2, 0), (\frac{12}{5}, -\frac{6}{5}, 4)\}$$

$$\bar{v}_2 = (3, 0, 4) - \frac{3}{5} \cdot (1, 2, 0) = (3, 0, 4) - (\frac{3}{5}, \frac{6}{5}, 0) = (\frac{12}{5}, -\frac{6}{5}, 4)$$

SNT
SUT

$$S \Rightarrow B_S = \{(\bar{v}_1, \bar{v}_2, \bar{v}_3) = \{(1, 1, 0, 0), (0, 0, 1, 0), (0, 0, 0, 1)\}$$

SNT = 0 edo SNT $\neq 0$

$$T \Rightarrow B_T = \{(\bar{v}_1, \bar{v}_2, \bar{v}_3) = \{(1, 1, 2, 1), (2, 0, 1, -1)\}$$

$$B_{S \cup T} = \{w_1, w_2, w_3\} = \{v_1\} = \{(1, 1, 2, 1)\}$$

$$v_1 \in T? \quad h(\bar{v}_1, \bar{v}_2, \bar{v}_3) = h \begin{pmatrix} 1 & 1 & 2 & 1 \\ 2 & 0 & 1 & -1 \\ 1 & 1 & 0 & 0 \end{pmatrix} = 3 \Rightarrow \text{ez da ortogonalak linea$$

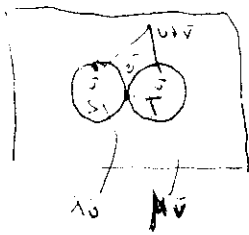
$$v_2 \in T? \quad h(\bar{v}_1, \bar{v}_2, \bar{v}_3) = h \begin{pmatrix} 1 & 1 & 2 & 1 \\ 2 & 0 & 1 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix} = 5$$

$$v_3 \in S? \quad h(\bar{v}_1, \bar{v}_2, \bar{v}_3, \bar{v}_4) = h \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 1 \end{pmatrix} = 3 \Rightarrow \text{Kombinazio linealak daude}$$

$$S / O_S = \{ (1, 2, 0) \} \dim S = 1$$

$$T / B_T = \{ (1, 0, 1) \} \dim T = 1$$

$$S \cap T = \vec{0} = (0, 0, 0)$$



$$\vec{u} + \vec{v} \in S \cap T? \quad \vec{u} + \vec{v} = (2, 2, 1) \quad \text{Er, kann sein dass, er da ein } \lambda \vec{u} + \mu \vec{v} \text{ notaken.}$$

Nutzen kalkulator einzeln beklare beklare haben Koordinaten

$$\begin{matrix} \updownarrow \\ \text{ELS} \end{matrix} \rightarrow \text{Forme matrizenale}$$

ELS Forme beklare

$$\begin{cases} x + 2y + 3z = 4 \\ x - y + z = 2 \\ x - z = 1 \end{cases}$$

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & -1 & 1 & 2 \\ 1 & 0 & -1 & 1 \end{pmatrix}$$

$$1(1, 1, 1) + 1(2, -1, 0) + 2(3, 1, -1) = (4, 2, 1)$$

gerne beklare

$$\vec{u}_1 = (1, 1, 1), \vec{u}_2 = (0, -1, 2)$$

$$\vec{k} = (-2, 5, -4) \in \mathbb{R}^3, \vec{u}_1, \vec{u}_2 \text{ komb. lineal berechnen}$$

$$\lambda_1 \vec{u}_1 + \lambda_2 \vec{u}_2 = \vec{k}$$

$$\lambda_1 (1, 1, 1) + \lambda_2 (0, -1, 2) = (-2, 5, -4)$$

$$\begin{bmatrix} \lambda_1 & \lambda_2 & -2 \\ \lambda_1 & -\lambda_2 & 5 \\ \lambda_1 & 2\lambda_2 & -4 \end{bmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & -2 \\ 1 & 1 & 5 \\ 1 & 2 & -4 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 3 \\ 0 & 2 & -6 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{matrix} h(A) = 2 \\ h(W) = 2 \end{matrix}$$

$$\sim \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 1 & -3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix}$$

$$\begin{matrix} \downarrow \\ \lambda_1 = 2 \\ \lambda_2 = -3 \end{matrix}$$

$$2(-1, 1, 1) + 3(0, -1, 2)$$

$$(-2, 2, 2) + (0, 3, -6)$$

$$(-2, 5, -4)$$

1

$$x \cdot \vec{a}_1 + y \cdot \vec{a}_2 + z \cdot \vec{a}_3 = \vec{b}$$

$$A := \begin{pmatrix} 1 & 1 & 2 & 3 \\ 2 & 0 & 3 & -4 \\ 3 & 1 & 4 & 5 \end{pmatrix} \quad A \cdot \vec{x} = \vec{b} \quad \begin{pmatrix} 1 & 1 & 2 & 3 \\ 2 & 0 & 3 & -4 \\ 3 & 1 & 4 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} = \begin{pmatrix} 3 \\ -4 \\ 5 \end{pmatrix}$$

$$x(1, 4, 3) + y(1, 0, -4) + z(2, 3, 4) = (3, -4, 5)$$

$$B_3 = \{ \vec{a}_1, \vec{a}_2, \vec{a}_3, \dots, \vec{a}_4 \}$$

$$\downarrow$$

$$h(B_3) = \begin{cases} \text{2. Zeile} \rightarrow \text{2. Spalte} \\ \text{1. Zeile} \rightarrow \text{1. Spalte} \end{cases}$$

$$\downarrow$$

dim. vekt. Unterraum

ELS BATERIAJONA SOLUTIO HURBISLOVA

$$x_1 + x_3 = 1$$

$$x_2 + 2x_3 = 1$$

$$x_1 + 2x_2 + 6x_3 = 1$$

$$x_1 + x_2 + 3x_3 = 1$$

$$A := \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 2 & 1 \\ 1 & 2 & 2 & 1 \\ 1 & 1 & 3 & 1 \end{pmatrix}$$

$\vec{a}_1, \vec{a}_2, \vec{a}_3$

$$h(A) \neq h(A')$$

$$B_3 = \{ (1, 0, 1, 1), (0, 1, 2, 1), (1, 2, 2, 3) \}$$

$$B_3 = x_1(1, 0, 1, 1) + x_2(0, 1, 2, 1) + x_3(1, 2, 2, 3)$$

$$x_1 \vec{a}_1 + x_2 \vec{a}_2 + x_3 \vec{a}_3 = \vec{b}$$

$$1) B_3 \rightarrow \text{dim. vekt.}$$

$$2) B_3 \rightarrow B_{B_3}$$

$$3) \vec{b} \text{ den } H(B_3) = \vec{b}$$

$$4) A \vec{x} = \vec{b} \rightarrow \text{S. bateragerrita}$$

$$5) \text{ Systeme esatze } \vec{x}: \text{ sol. hurbislou}$$

$$h(B_3) = 3 \text{ dim. vekt.}$$

$$\text{GRAM-SCHMIDT} \Rightarrow B_{B_3} = \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \}$$

$$\vec{v}_1 = \vec{u}_1 = (1, 0, 1, 1)$$

$$\langle \vec{u}_2, \vec{v}_1 \rangle = 3$$

$$\langle \vec{u}_3, \vec{v}_1 \rangle = 6$$

$$\langle \vec{u}_3, \vec{v}_2 \rangle = 3$$

$$\|\vec{v}_1\|^2 = 3$$

$$\|\vec{v}_2\|^2 = 3$$

$$\vec{v}_2 = \vec{u}_2 - P_{\vec{v}_1} \vec{u}_2 = \vec{u}_2 - \frac{\langle \vec{u}_2, \vec{v}_1 \rangle}{\|\vec{v}_1\|^2} \vec{v}_1 = \vec{u}_2 - \frac{3}{3} \vec{v}_1 = \vec{u}_2 - \vec{v}_1$$

$$\vec{v}_3 = \vec{u}_3 - P_{\vec{v}_1} \vec{u}_3 - P_{\vec{v}_2} \vec{u}_3 = \vec{u}_3 - \frac{6}{3} \vec{v}_1 - \frac{3}{3} \vec{v}_2 = \vec{u}_3 - 2\vec{v}_1 - \vec{v}_2$$

$$\vec{v}_2 = (0, 1, 2, 1) - (1, 0, 1, 1) = (-1, 1, 1, 0)$$

$$\vec{v}_3 = (1, 2, 2, 3) - (2, 0, 2, 2) - (-1, 1, 1, 0) = (0, 1, -1, 1)$$

$$B_{B_3} = \{ (1, 0, 1, 1), (-1, 1, 1, 0), (0, 1, -1, 1) \}$$

$\Delta \bar{x} = \bar{b}$ \bar{b} re. HL System

$\bar{b} = \sum_{i=1}^3 P_{v_i} \bar{b} = P_{v_1} \bar{b} + P_{v_2} \bar{b} + P_{v_3} \bar{b}$

$\bar{b} = (1, 1, 1, 1)$

$\frac{\langle \bar{b}, \bar{v}_1 \rangle}{\|\bar{v}_1\|^2} \bar{v}_1 + \frac{\langle \bar{b}, \bar{v}_2 \rangle}{\|\bar{v}_2\|^2} \bar{v}_2 + \frac{\langle \bar{b}, \bar{v}_3 \rangle}{\|\bar{v}_3\|^2} \bar{v}_3$

$\frac{3}{5} \bar{v}_1 + \frac{1}{3} \bar{v}_2 + \frac{1}{3} \bar{v}_3$

$\bar{v}_1 + \frac{1}{3} (\bar{v}_2 + \bar{v}_3)$

$(1, 0, 1, 1) + \frac{1}{3} (-1, 2, 0, 1)$

$(1, 0, 1, 1) + (-1/3, 2/3, 0, 1/3)$

$(2/3, 2/3, 1, 4/3)$

$\langle \bar{b}, \bar{v}_1 \rangle = 3$

$\langle \bar{b}, \bar{v}_2 \rangle = 1$

$\langle \bar{b}, \bar{v}_3 \rangle = 1$

$\|\bar{v}_1\|^2 = 5$

$\|\bar{v}_2\|^2 = 3$

$\|\bar{v}_3\|^2 = 3$

$\Delta \cdot \bar{x} = \bar{b} \Rightarrow \Delta \bar{x} = \bar{b}$

$\Delta \bar{z}^* = \begin{pmatrix} 1 & 0 & 1 & -4/3 \\ 0 & 1 & 2 & -4/3 \\ 1 & 2 & 2 & -1 \\ 1 & 1 & 3 & -1/3 \end{pmatrix}$

$h(A) = h(A_1) = 3$

$\begin{pmatrix} 1 & 0 & 0 & 1/3 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1/3 \end{pmatrix} \begin{matrix} \lambda_1 = 1/3 \\ \lambda_2 = 0 \\ \lambda_3 = 1/3 \end{matrix}$

$e \cdot d(\bar{b}, \bar{b}^*) = \|\bar{b} - \bar{b}^*\|$

$= \|(1/3, 1/3, 0, -1/3)\|$

$= + \sqrt{(1/3)^2 + (1/3)^2 + (-1/3)^2}$

$= + \sqrt{\frac{1+1+1}{9}} = + \sqrt{\frac{3}{9}} = + \sqrt{1/3}$

$h(A) \leq 3$

$h(A_1) \leq 4$

SB

Det h = 5

Indet [uninvertierbar] h = 2

$h(A) = h(A_1)$

det A \leftrightarrow A's polynomial charakteristika

$|A - \lambda I| = 0 \quad / \quad A \in \mu_{n \times n}(\mathbb{R}) ; \sigma(A) = \{\lambda_1(k_1), \lambda_2(k_2), \dots\}$

$(-1)^n \cdot P_n(\lambda) = (-1)^n \cdot (\lambda - \lambda_1)^{k_1} \cdot (\lambda - \lambda_2)^{k_2} \cdot \dots$

$k_1 + k_2 + \dots = n$

$|A - \lambda I|_{\lambda=0} \Rightarrow |A| = [(-1)^n \cdot P_n(\lambda)]_{\lambda=0}$

A3.5

$\sigma(A) = \{1(k=1), -2(k=1), 3(k=1)\} \quad / \quad A \in \mu_{3 \times 3}(\mathbb{R})$

$P(\lambda) = [(\lambda - 1)(\lambda + 2)(\lambda - 3)]_{\lambda=0} \quad |A| = (-1)(-1)(-3) = -6$

[uninvertierbar]

$\sigma(A) = \{2(k=2), -3(k=1)\} \rightarrow \{2, 2, -3\}$

$(-1)^3 P(\lambda) = (-1)^3 [(\lambda - 2)^2 (\lambda + 3)]_{\lambda=0}$

$|A| = -12 \quad (-1)(-1)(-3)$

Eigenvalues []

Eigenvectors []

Eigensystem []

$$D_{\text{neu}} / \vec{v}(0) = \{1, -3, 2, 0\}$$

$$(-1)^4 P(\lambda) = [(1 - (\lambda - 1)(\lambda + 3)(\lambda - 2)(\lambda - 0))]_{\lambda=0}$$

$$|A| = 1 \cdot (-1) \cdot (-3) \cdot (-2) \cdot 0 = 0$$

$$S = \left\{ \begin{pmatrix} a+b+3c & 2a-b \\ -2-c & a+2b+5c \end{pmatrix} \mid a, b, c \in \mathbb{R} \right\}$$

$$a(1, 2, -1, 1) + b(1, -1, 0, 1) + c(3, 0, -1, 5)$$

$$h(G_3) = h \begin{pmatrix} 1 & 2 & -1 & 1 \\ 1 & -1 & 0 & 1 \\ 3 & 0 & -1 & 5 \end{pmatrix} = h \begin{pmatrix} 1 & 2 & -1 & 1 \\ 0 & -3 & 1 & 1 \\ 0 & -6 & 2 & 2 \end{pmatrix} = h \begin{pmatrix} 1 & 2 & -1 & 1 \\ 0 & -3 & 1 & 1 \\ 0 & -3 & -1 & 1 \end{pmatrix} = h$$

Bemerkung: bei einer Dimensions-Veränderung

$$G_3 = \left\{ \begin{pmatrix} 1 & 2 \\ -1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & -1 \\ 0 & 2 \end{pmatrix}, \begin{pmatrix} 3 & 0 \\ 1 & 5 \end{pmatrix} \right\} \quad B_0 = \{ \vec{e}_1, \vec{e}_2 \}$$

$$a \vec{e}_1 + b \vec{e}_2 + c \vec{e}_3$$

$$\vec{u} = (1, 2, -1)$$

$$\vec{v} = (0, 1, 3)$$

$$\langle \vec{u}, \vec{v} \rangle = 0 + 2 - 3 = -1$$

$$\|\vec{u}\| = \sqrt{\langle \vec{u}, \vec{u} \rangle} = \sqrt{1^2 + 2^2 + (-1)^2} = \sqrt{6}$$

$$\|\vec{v}\| = \sqrt{0^2 + 1^2 + 3^2} = \sqrt{10}$$

$$d(\vec{u}, \vec{v}) = \|\vec{u} - \vec{v}\| = \|(1, 1, 4)\|$$

$$P_{\vec{u}} \vec{u} = \frac{\langle \vec{u}, \vec{u} \rangle}{\|\vec{u}\|^2} \cdot \vec{u}$$

$$P_{\vec{v}} \vec{v} =$$

$$|A - \lambda I| = \begin{vmatrix} 1-\lambda & 0 & 0 & 0 \\ 0 & 1-\lambda & 0 & -1 \\ 0 & 0 & 1-\lambda & -1 \\ 0 & -1 & -1 & 2-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} -1-\lambda & 0 & -1 \\ 0 & -1-\lambda & -1 \\ -1 & -1 & 2-\lambda \end{vmatrix} = (-1)^3 (1-\lambda) \begin{vmatrix} 1+\lambda & 0 & 1 \\ 0 & 1+\lambda & 1 \\ 1 & 1 & 2-\lambda \end{vmatrix}$$

< Linear Algebra > orthogonale! per Characteristisches Polynom!

$$\begin{pmatrix} [(-1-\lambda)(-1-\lambda)(2-\lambda)] - [(-1-\lambda) + (-1-\lambda)] \\ (1+\lambda)^2 (2-\lambda) - (-2-2\lambda) \\ -2-4\lambda-2\lambda^2-\lambda-2\lambda^2-\lambda^3+2+2\lambda \\ -\lambda^3-4\lambda^2-3\lambda \end{pmatrix}$$



$$(1-\lambda) (-\lambda^3 - 4\lambda^2 - 3\lambda)$$

$$\begin{pmatrix} (1+\lambda)(1+\lambda)(2+\lambda) - (1+\lambda) - (1+\lambda) \\ (1+\lambda+\lambda+\lambda^2)(2+\lambda) - 2(1+\lambda) \\ -2+4\lambda+2\lambda^2+\lambda+2\lambda^2+\lambda^3-2+2\lambda \\ \lambda^3+4\lambda^2+3\lambda \end{pmatrix}$$



$$(1-\lambda) (\lambda^3 + 4\lambda^2 + 3\lambda)$$

$$(1-\lambda) [(1+\lambda)^2 (2+\lambda) - (1+\lambda) - (1+\lambda)] = (1-\lambda) (1+\lambda) [(1+\lambda)(2+\lambda) - 2]$$

$$(\lambda - 1)(\lambda + 1) [\lambda^2 + 3\lambda + 2 - 2] = 0 \Rightarrow (\lambda - 1)(\lambda + 1) \lambda (\lambda + 3) = 0$$

$$\begin{array}{l} \lambda = 1 \\ \lambda = -1 \\ \lambda = 0 \\ \lambda = -3 \end{array}$$

ELS - HOMOGENEOUS

↓
Form matrix

$$(A - \lambda I) \mathbf{x} = \mathbf{0}_{n \times 1}$$

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$$

$$(A - \lambda I)_{\lambda=0} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & -1 & -1 & 0 \\ 0 & -1 & -1 & -2 & 0 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{pmatrix}$$

$$h(A) = h(A - \lambda I) = 3 < 4 \quad \left\{ \begin{array}{l} \text{Erstes} \rightarrow 3 \\ \text{Zweites} \rightarrow 1 \end{array} \right.$$

$$x_1 = 0$$

$$x_2 + x_4 = 0$$

$$x_3 + x_4 = 0$$

$$x_1 = 0$$

$$x_2 = x_3 = -x_4$$

Dimension: 1

1) Guess

2) Rouché-Fröbenius \rightarrow Erstes \rightarrow dim S(A)

3) CASIO CALCULATOR